

Probabilistic Taken's Embedding through the Wasserstein Tangent Space

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Embeddings



Notion of „sameness“

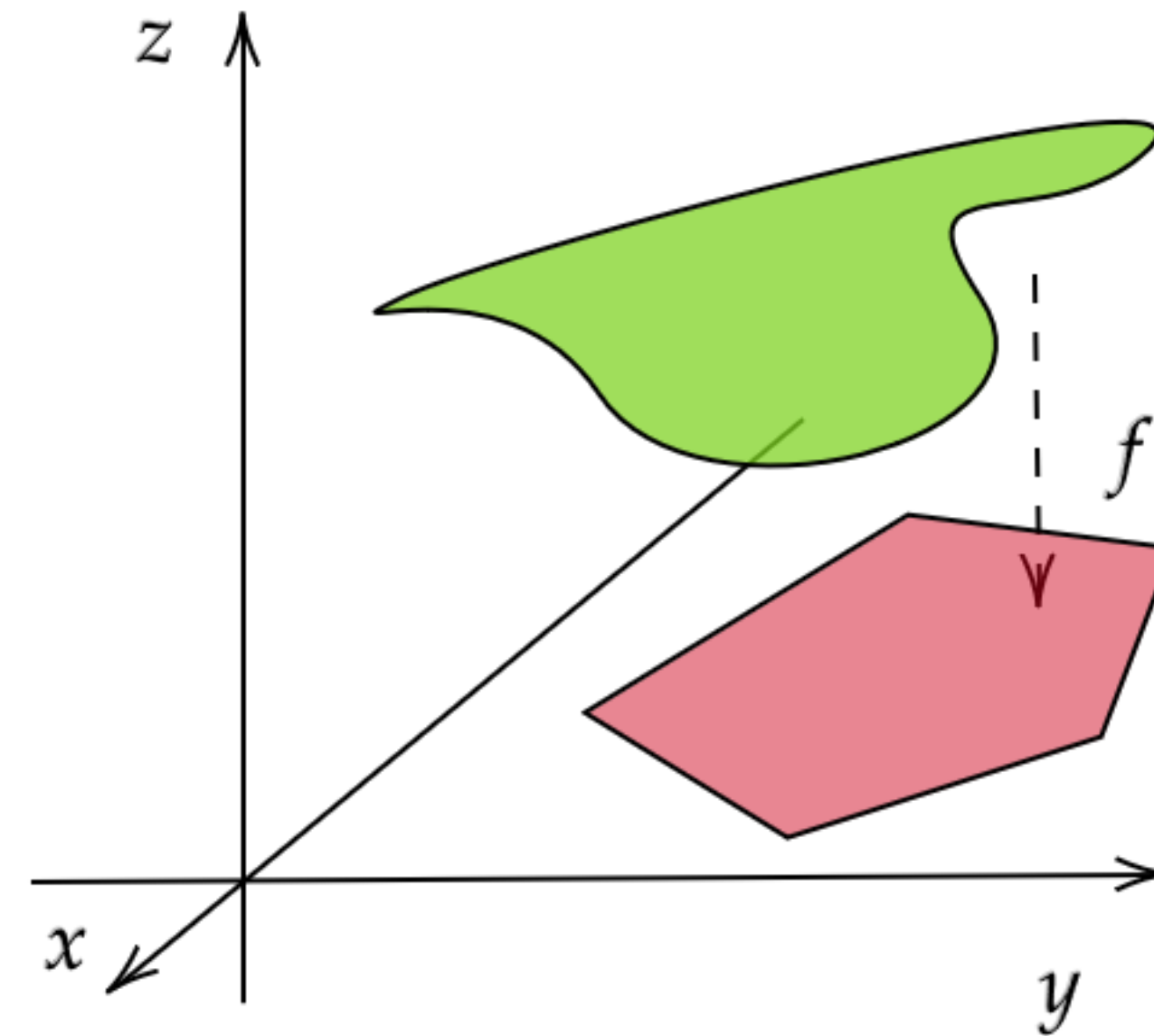


Diffeomorphism that **preserves the differential structure**



$f: M \rightarrow N$ is an **embedding** if

- f is **bijective** onto $f(M)$
- f is **differentiable**
- Df_x is **injective**



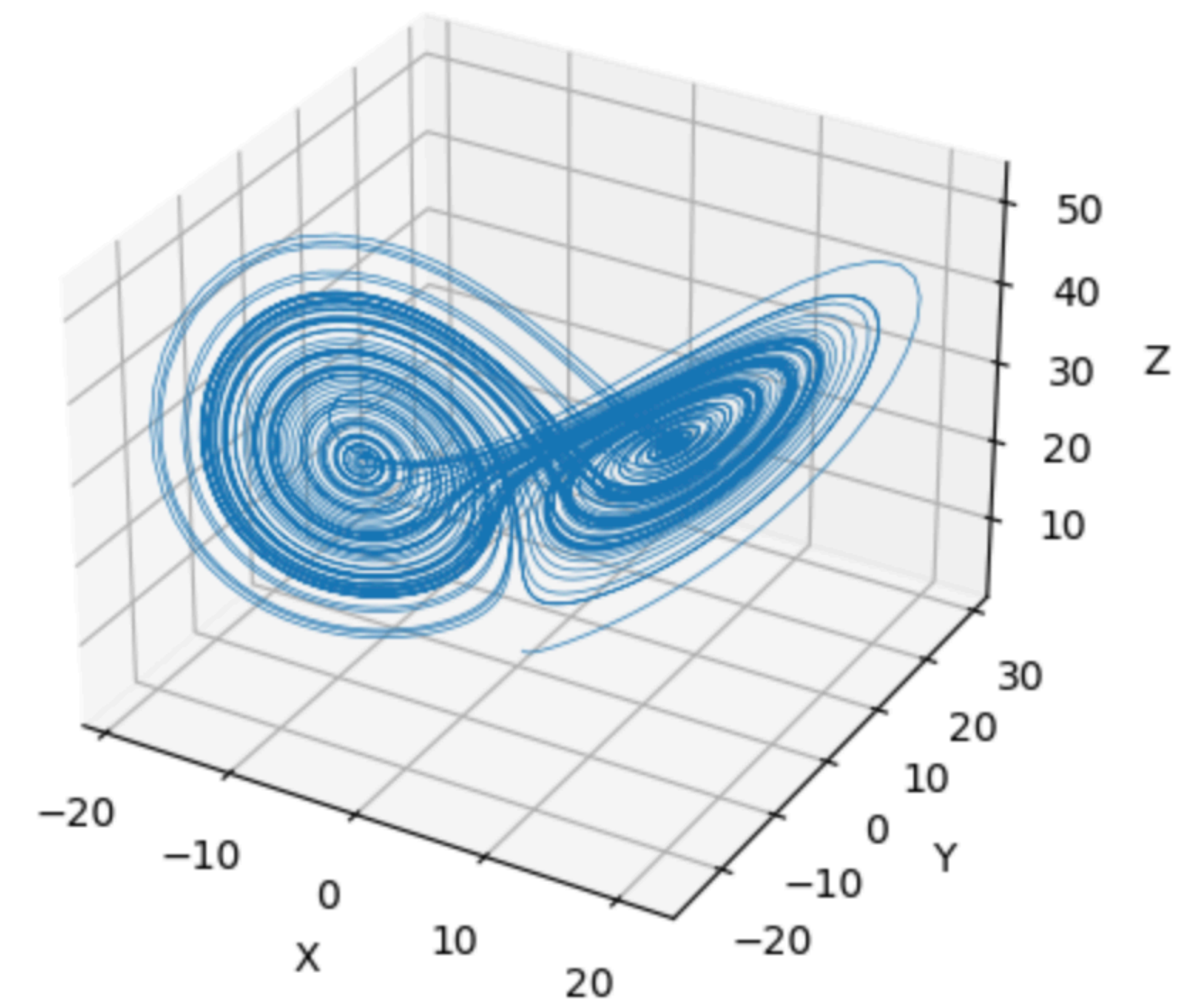
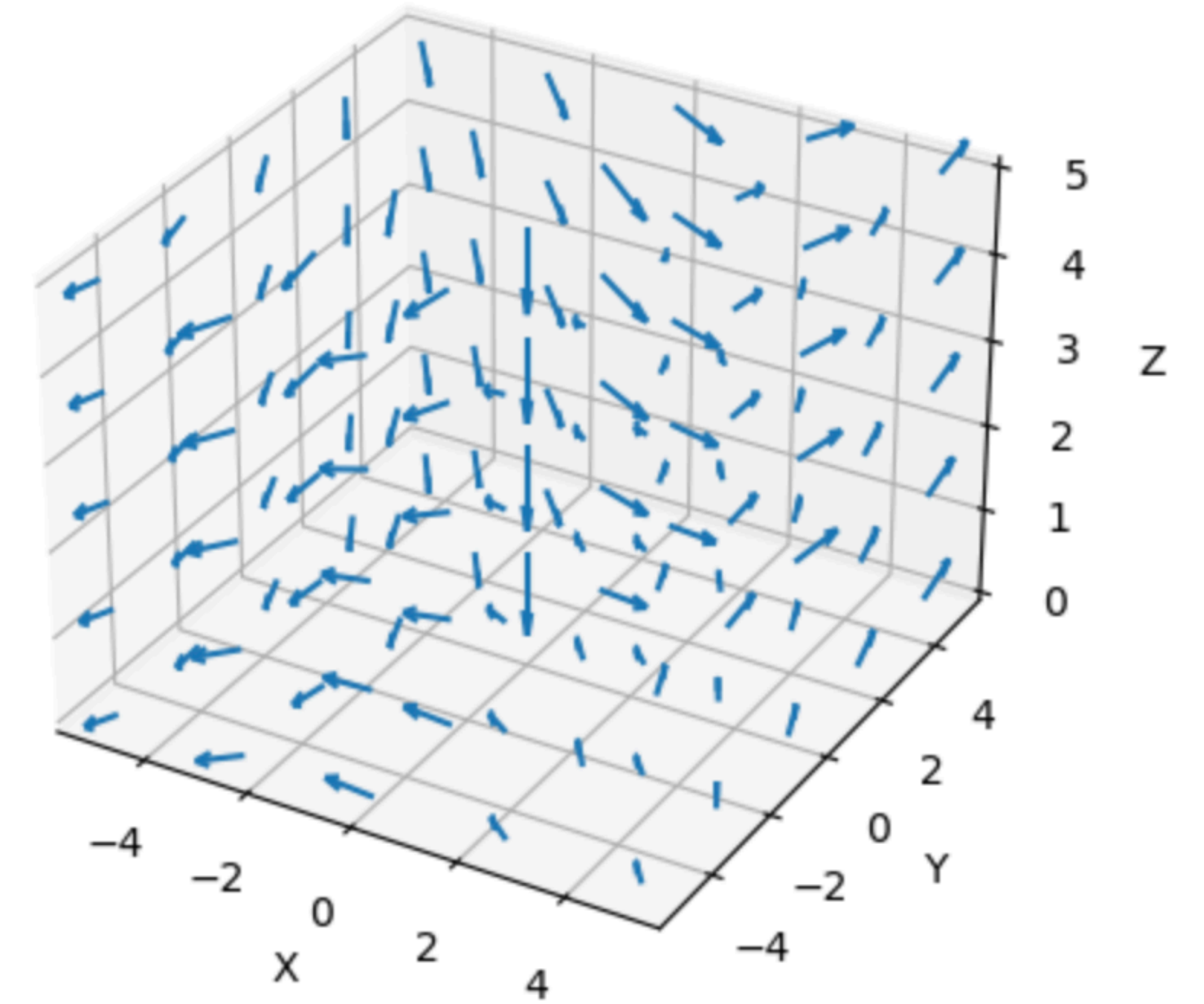
Takens embedding

- ✿ $\dot{x} = f(x)$ with flow $\varphi_t : M \rightarrow M$
- ✿ $h : M \rightarrow \mathbb{R}$ is the **observation** function
- ✿ It is a **generic** propriety that the **delay** map

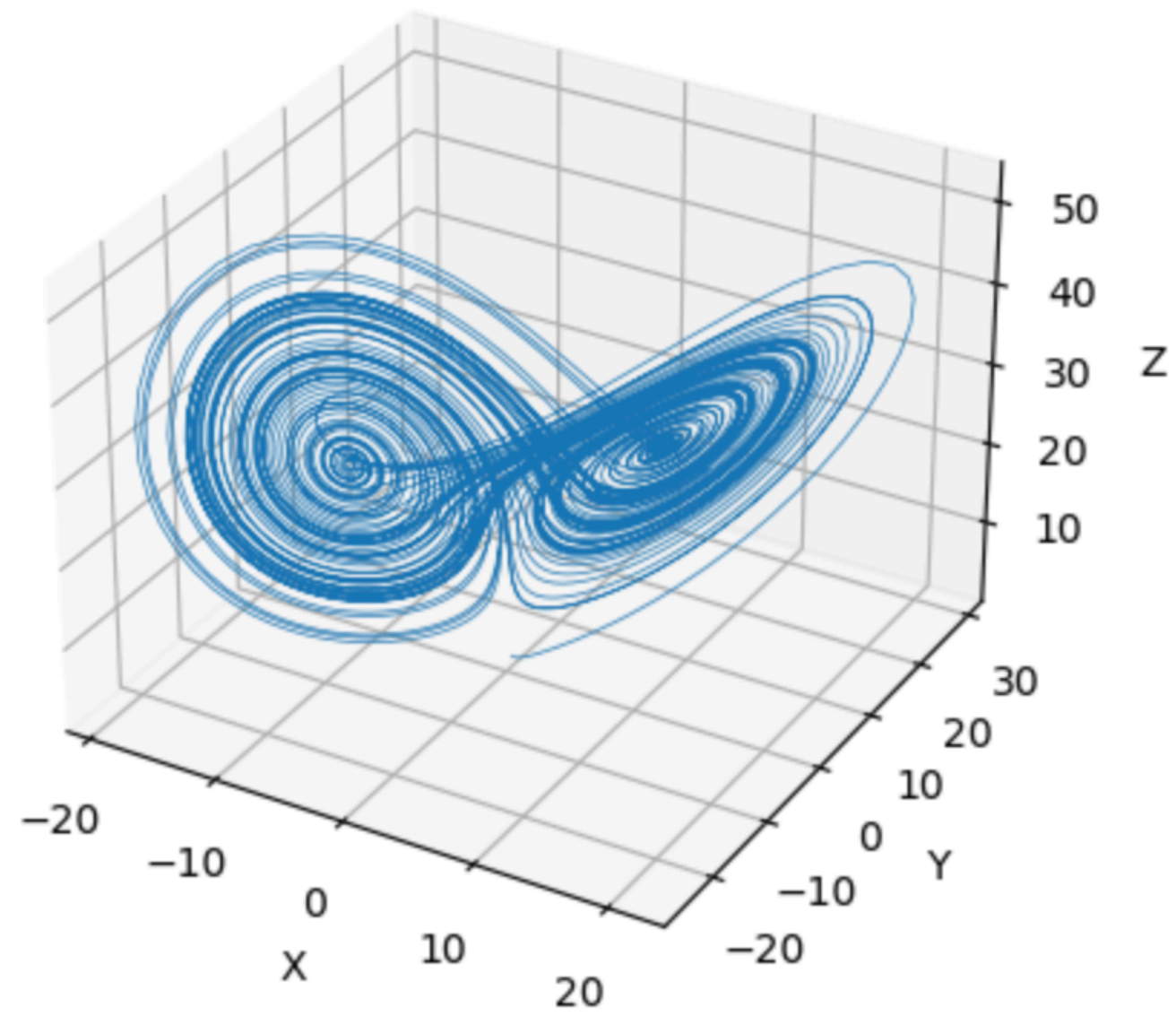
$$\Phi_{h,\varphi_t}(x) = (h(x), h(\varphi_\tau(x)), \dots, h(\varphi_{(d-1)\tau}(x)))$$

is an **embedding**

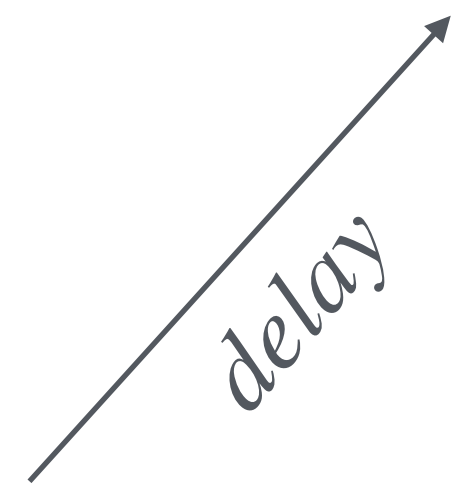
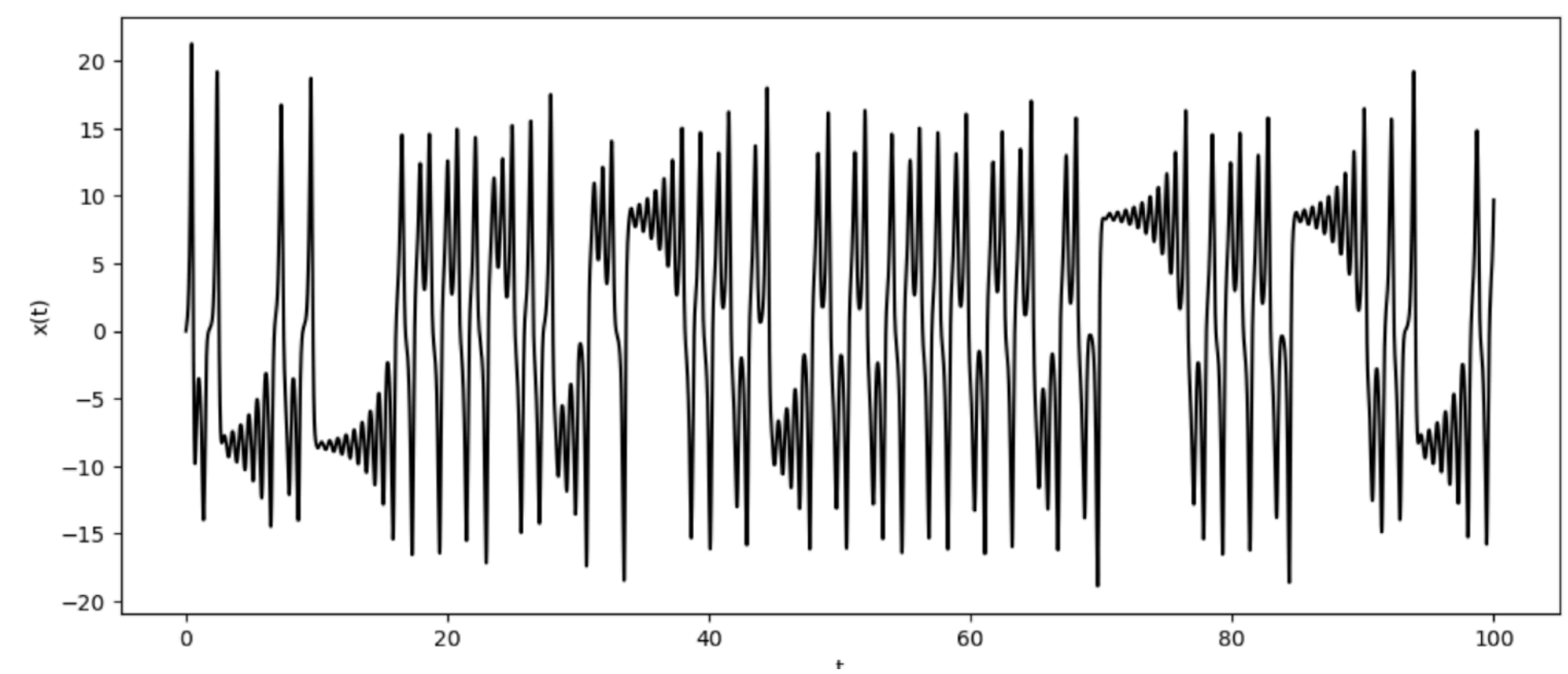
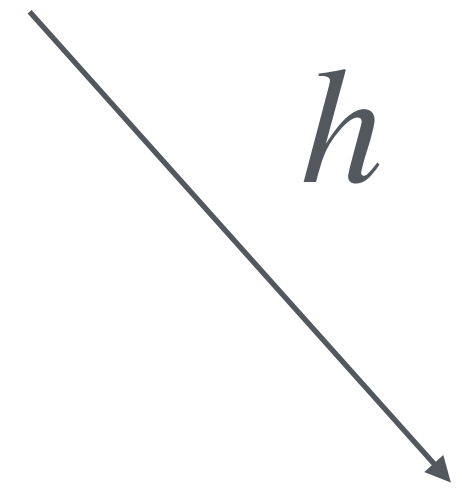
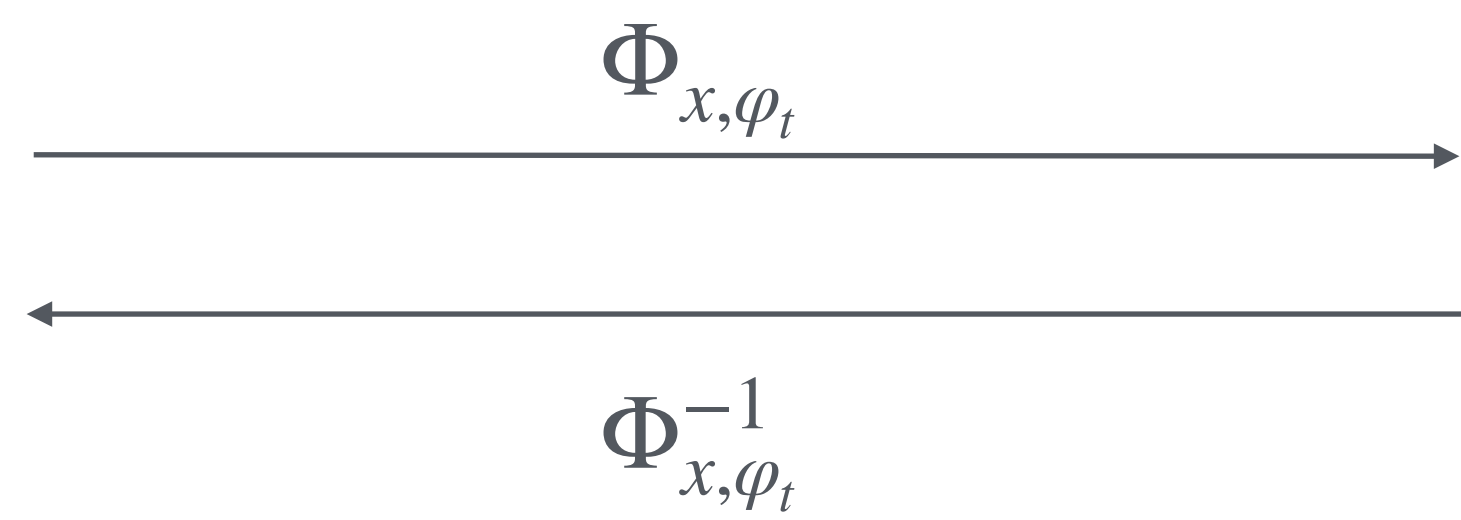
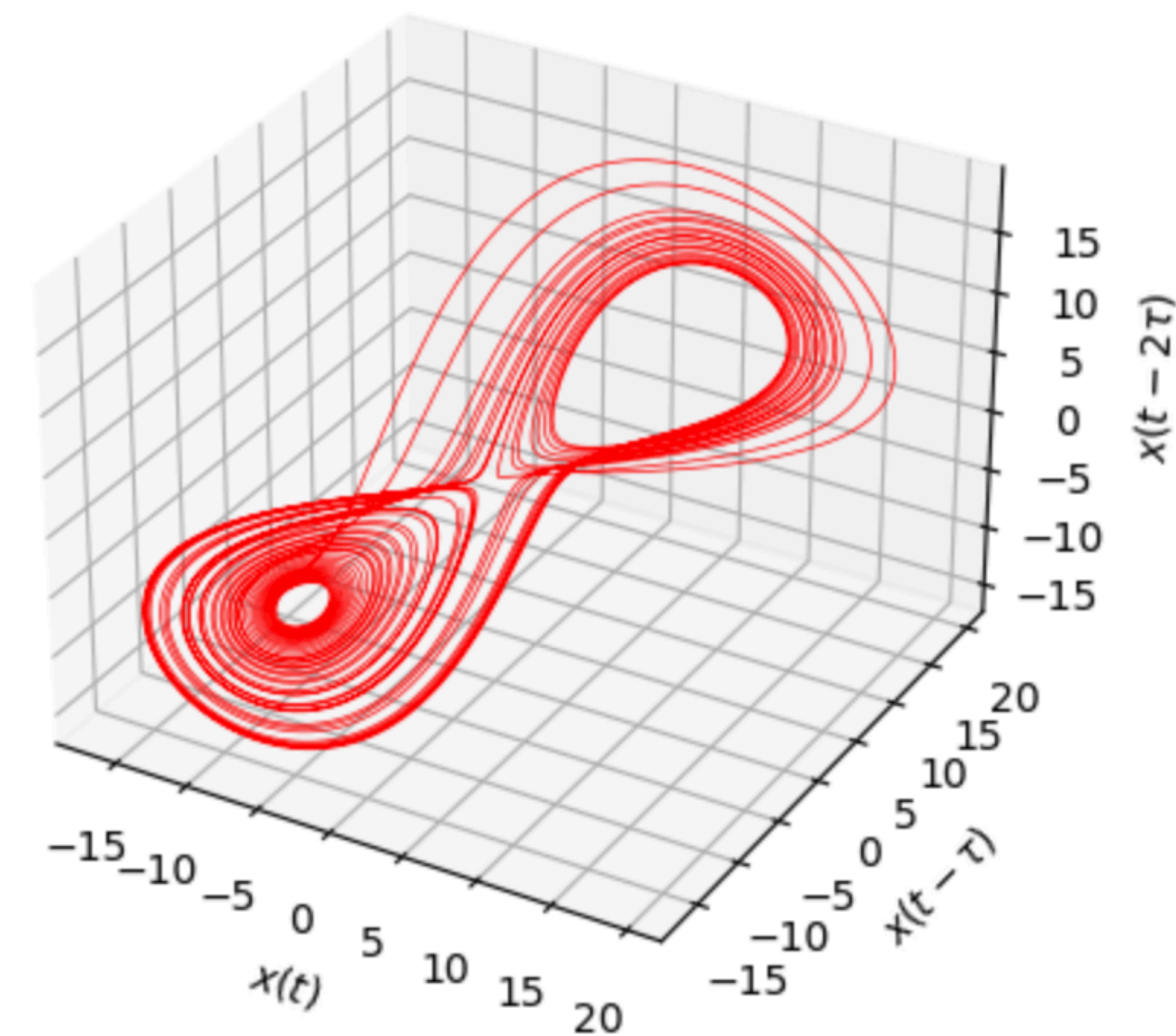
- ✿ τ is called the delay, and d is the dimension



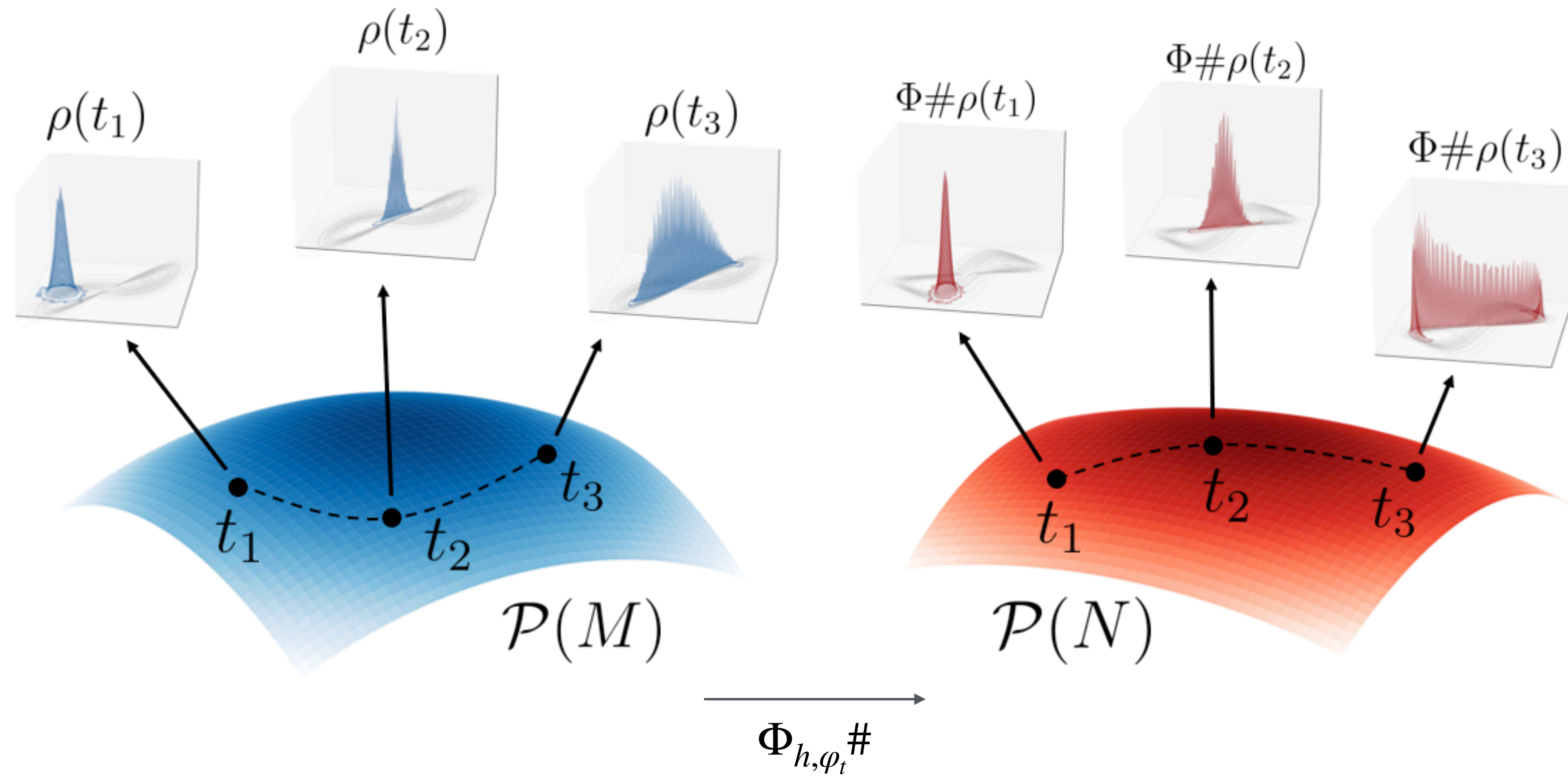
M



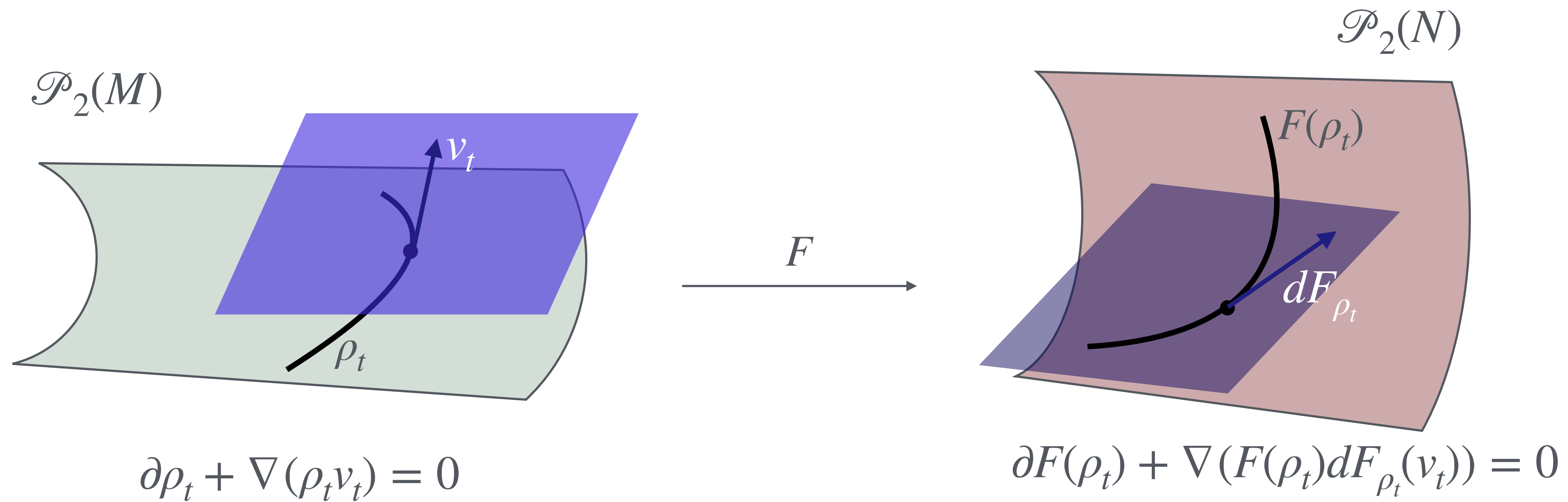
N



Lifted Takens embedding



Wasserstein embedding



* If $F = f\#$ then $dF_{\rho_t}(v_t)(y) = P_{F(\rho_t)} df_{f^{-1}(y)} v_t(f^{-1}(y))$

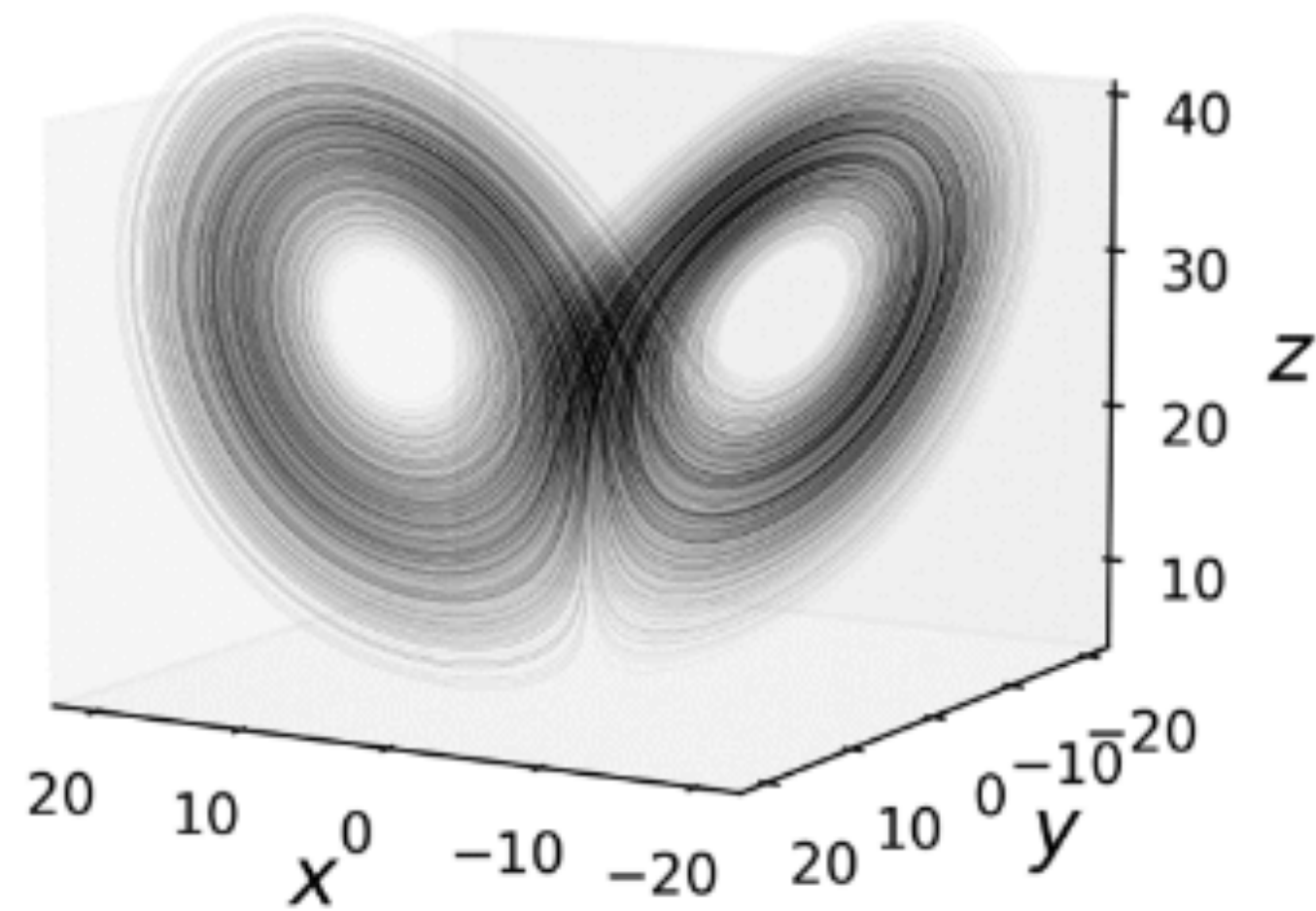
Numerical result

Reconstruction map

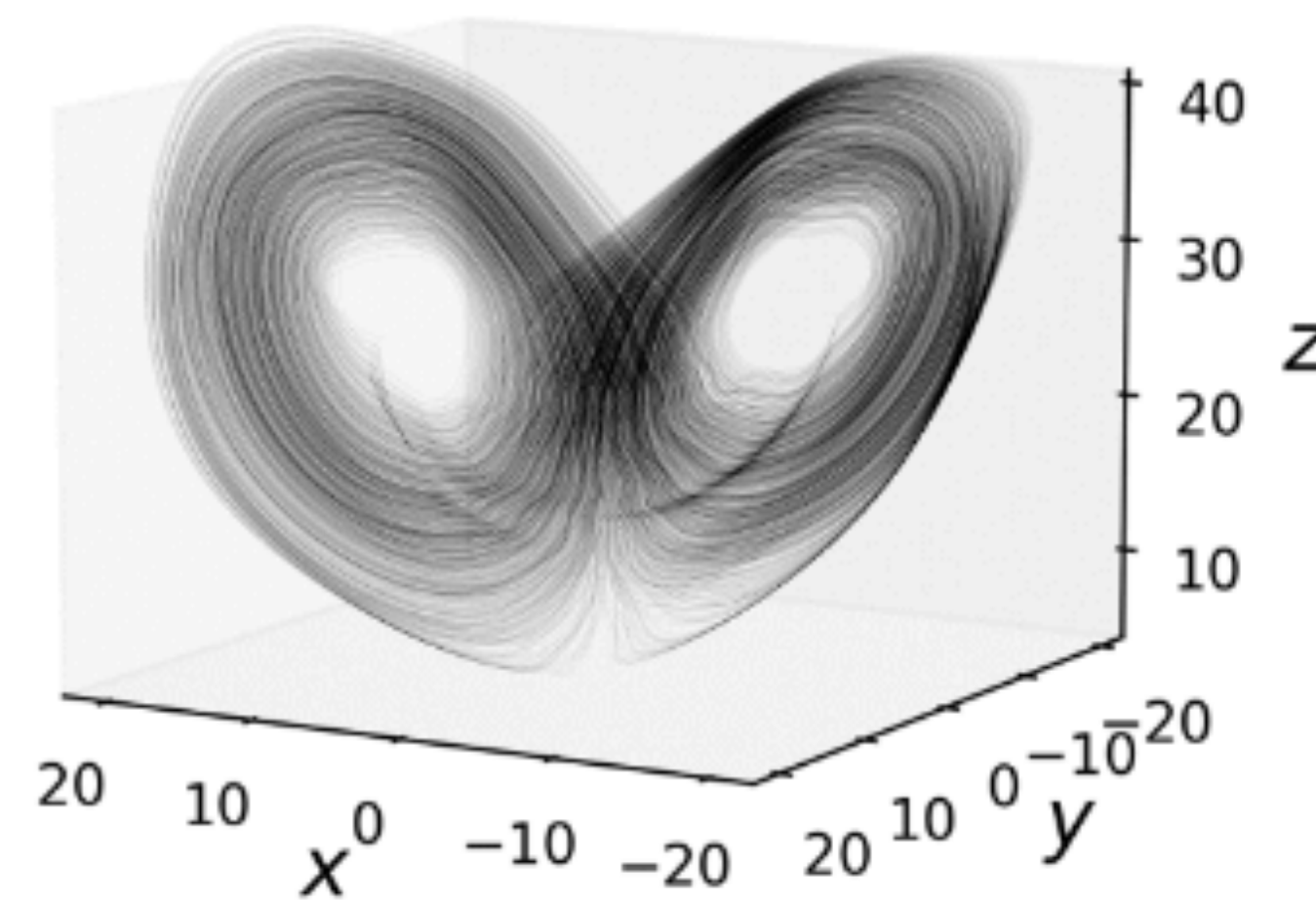
$$L_m = \frac{1}{M} \sum_{i=1}^M D(\mu_i, R_\theta \# \Phi \# \mu_i)$$

$$L_{pw} = \frac{1}{N} \sum_{i=1}^n \|x_i - R_\theta(\Phi(x_i))\|^2$$

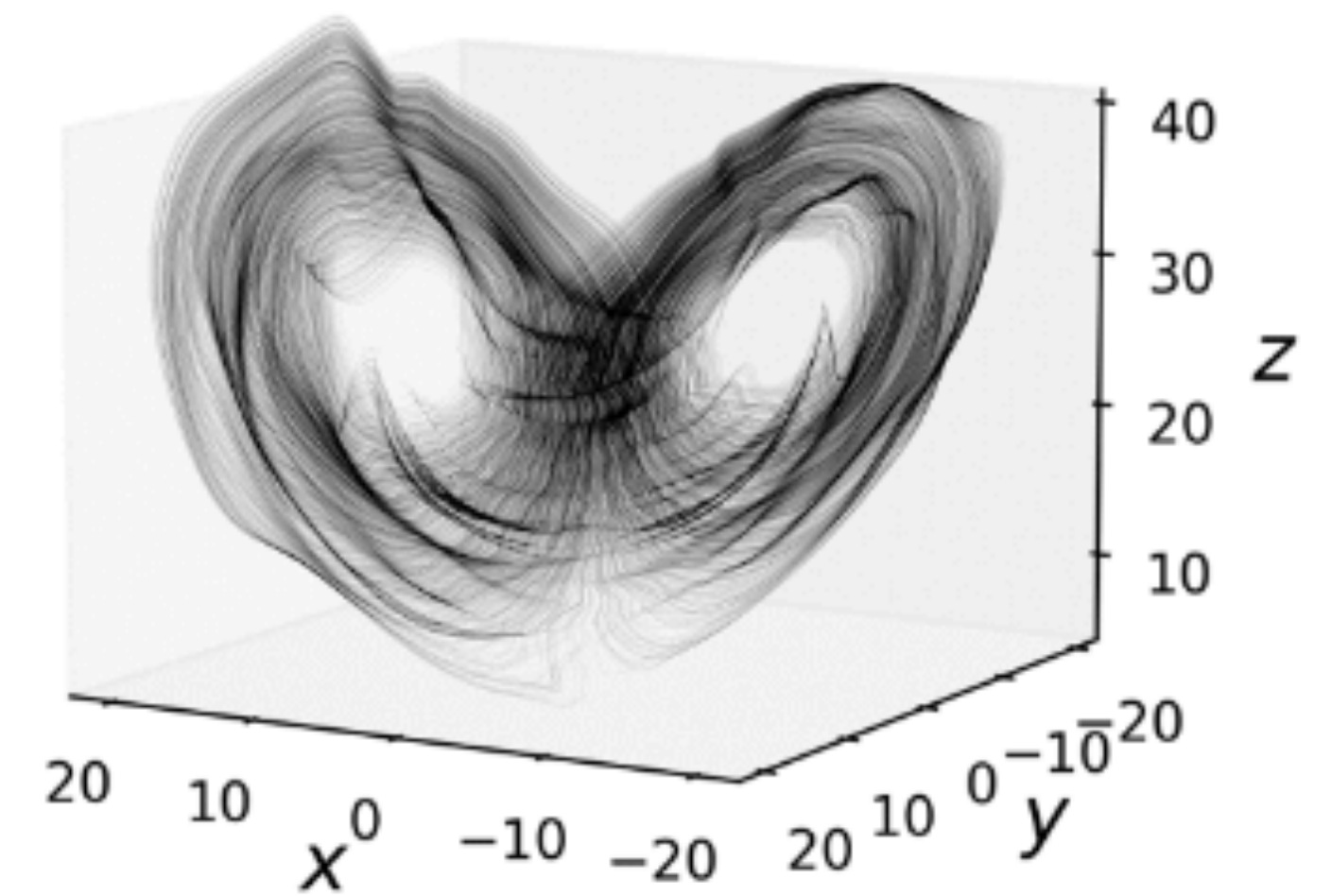
Ground Truth



Measure-Based Reconstruction



Pointwise Reconstruction



0.1I noise